

TD 13. Algèbre 2

$$p \circ p = p$$

$$p(p(x)) = p(x)$$

Exercice 1.

• Si $x + p(x) = b$ alors $p(x + p(x)) = p(b)$
donc $p(x) + \underbrace{p(p(x))}_{p(x)} = p(b)$

donc $p(x) = \frac{p(b)}{2}$.

Donc $x = b - p(x) = b - \frac{p(b)}{2}$.

• Posons $x = b - \frac{p(b)}{2}$.

Alors $x + p(x) = b - \frac{p(b)}{2} + p(b) - \frac{p(p(b))}{2} = b$.

Exercice 2.

1. • $F \cap G = \{(0, 0, 0, 0)\}$:

Soit $(x, y, z, t) \in F \cap G$.

On a $x = -y$ et $z = -t$.

On a $(x, y, z, t) = \lambda_1 (1, 1, 0, 0) + \lambda_2 (1, 1, 1, 1)$
 $= (\lambda_1 + \lambda_2, \lambda_1 + \lambda_2, \lambda_2, \lambda_2)$ où $\lambda_1, \lambda_2 \in \mathbb{R}$.

Donc $\begin{cases} \lambda_1 + \lambda_2 = -\lambda_1 - \lambda_2 \\ \lambda_2 = -\lambda_2 \end{cases}$ donc $\begin{cases} \lambda_2 = 0 \\ \lambda_1 = 0 \end{cases}$.

Donc $(x, y, z, t) = (0, 0, 0, 0)$.

• $\dim G = 2$

$F = \{(x, -x, z, -z), (x, z) \in \mathbb{R}^2\}$

$= \text{Vect}((1, -1, 0, 0), (0, 0, 1, -1))$, donc $\dim F = 2$.

Donc $\dim F + \dim G = 4 = \dim \mathbb{R}^4$.

Donc $\mathbb{R}^4 = F \oplus G$.

2. Pour tout $(x, y, z, t) \in \mathbb{R}^4$,

$$(x, y, z, t) = \underbrace{(x_f, y_f, z_f, t_f)}_{\in F} + \underbrace{(x_g, y_g, z_g, t_g)}_{\in G}.$$

Aussi $p((x, y, z, t)) = (x_f, y_f, z_f, t_f) = (x_f, -x_f, z_f, -z_f)$

Donc $(x, y, z, t) = (x_f, -x_f, z_f, -z_f) + \lambda_1(1, 1, 0, 0) + \lambda_2(1, 1, 1, 1)$
 $= (x_f + \lambda_1 + \lambda_2, -x_f + \lambda_1 + \lambda_2, z_f + \lambda_2, -z_f + \lambda_2).$

$$\begin{cases} x = x_f + \lambda_1 + \lambda_2 \\ y = -x_f + \lambda_1 + \lambda_2 \\ z = z_f + \lambda_2 \\ t = -z_f + \lambda_2 \end{cases}$$

$$\lambda_2 = \frac{z+t}{2}$$

$$z_f = z - \frac{z+t}{2} = \frac{z-t}{2}$$

$$\lambda_1 + \lambda_2 = \frac{x+y}{2}$$

$$\lambda_1 = \frac{x+y}{2} - \frac{z+t}{2}$$

$$x_f = x - \frac{x+y}{2}$$

$$= \frac{x-y}{2}$$

Donc $p((x, y, z, t)) = \left(\frac{x-y}{2}, \frac{y-x}{2}, \frac{z-t}{2}, \frac{t-z}{2} \right)$.

Donc $\text{mat}_{B_C} p = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 & 0 \\ 0 & 0 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & 0 & -\frac{1}{2} & -\frac{1}{2} \end{pmatrix}$.

$p((1, 0, 0, 0)) = \left(\frac{1}{2}, -\frac{1}{2}, 0, 0 \right),$

⋮

ou $B_1 = \left(\begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix} \right)$ base de F

$$\vec{x} = \begin{matrix} \vec{p} \\ \in F \end{matrix} + \begin{matrix} \vec{g} \\ \in G \end{matrix}$$

$B_2 = \left(\begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right)$ base de G .

$$p(\vec{x}) = \vec{p}$$

Posons $\mathcal{B} = (\mathcal{B}_1, \mathcal{B}_2) = \left(\left(\begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} \right), \left(\begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix} \right), \left(\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right), \left(\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \right) \right) = (u_1, u_2, u_3, u_4)$

$$A = \text{mat}_{\mathcal{B}} p = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$p\left(\begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} = 1u_1 + 0u_2 + 0u_3 + 0u_4 \quad p(u_1) = u_1$$

$$p(u_2) = u_2$$

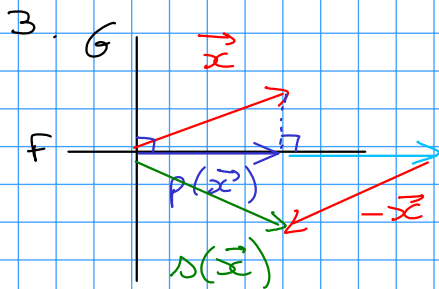
$$u_2 = u_2 + 0 \quad p(u_2) = u_2$$

$$u_3 = \underbrace{0}_{\in F} + \underbrace{u_3}_{\in G} \quad , \quad p(u_3) = 0$$

$$\text{mat}_{\mathcal{B}_c} p = \underbrace{\begin{pmatrix} \mathcal{B}_1 \\ \mathcal{B}_c \end{pmatrix}}_P A \underbrace{\mathcal{B}_c}_{\mathcal{B}} = PAP^{-1}$$

$$P = \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & -1 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & -1 & 0 & 1 \end{pmatrix}$$

Calculer P^{-1} , puis PAP^{-1} .



$$s(\vec{x}) = 2p(\vec{x}) - \vec{x}$$

$$s = 2p - \text{id}$$

$$\text{mat}_{\mathcal{B}_c} s = 2 \text{mat}_{\mathcal{B}_c} p - \text{mat}_{\mathcal{B}_c} \text{id}$$

$$= 2 \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{2} & -\frac{1}{2} \\ 0 & 0 & -\frac{1}{2} & \frac{1}{2} \end{pmatrix} - \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$\vec{i} (1, 0, 0)$$

$$\vec{j} (0, 1, 0)$$

$$\vec{k} (0, 0, 1)$$

$$\vec{v} (1, 1, 1)$$

Exercice 4

$$1. \quad f((x, y, z)) = \left(\frac{2}{3}x - \frac{1}{3}y - \frac{1}{3}z, -\frac{1}{3}x + \frac{2}{3}y - \frac{1}{3}z, -\frac{1}{3}x - \frac{1}{3}y + \frac{2}{3}z \right)$$

$$A = \text{mat}_{\mathbb{R}^3} f = \frac{1}{3} \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix}$$

2 - Soit $(x, y, z) \in \mathbb{R}^3$.

$$(x, y, z) \in \text{ker } f \quad \text{ssi} \quad \frac{1}{3} \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{ssi} \quad \begin{cases} 2x - y - z = 0 \\ -x + 2y - z = 0 \\ -x - y + 2z = 0 \end{cases}$$

$$\text{ssi} \quad \begin{cases} x + y - 2z = 0 \\ -x + 2y - z = 0 \\ -x - y + 2z = 0 \end{cases}$$

$$\text{ssi} \quad \begin{cases} x + y - 2z = 0 \\ y = z \end{cases}$$

$$\text{ssi} \quad \begin{cases} y = z \\ x = y \end{cases}$$

$$\text{ssi} \quad (x, y, z) = x (1, 1, 1)$$

Donc $\text{ker } f = \text{Vect}((1, 1, 1))$. $((1, 1, 1))$ base de $\text{ker } f$.

On a $\dim \ker f = 1$ et $\dim \operatorname{Im} f = 3 - 1 = 2$.

$\begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} \in \operatorname{Im} f$, non colinéaires donc forment une famille libre de $\operatorname{Im} f$, composée de 2 éléments et $\dim \operatorname{Im} f = 2$.

Donc $(2, -1, -1), (-1, 2, -1)$ base de $\operatorname{Im} f$.

• $\dim \ker f + \dim \operatorname{Im} f = 3$.

• $\ker f \cap \operatorname{Im} f = \{(0, 0, 0)\}$.

Soit $(x, y, z) \in \ker f \cap \operatorname{Im} f$.

$$\begin{aligned} (x, y, z) &= \lambda_1 (2, -1, -1) + \lambda_2 (-1, 2, -1) \\ &= (2\lambda_1 - \lambda_2, -\lambda_1 + 2\lambda_2, -\lambda_1 - \lambda_2) \end{aligned}$$

$$\text{et } \begin{cases} 2\lambda_1 - \lambda_2 = -\lambda_1 - \lambda_2, \\ -\lambda_1 + 2\lambda_2 = -\lambda_1 - \lambda_2, \end{cases} \text{ donc } \begin{cases} \lambda_1 = 0, \\ \lambda_2 = 0. \end{cases}$$

D'où $\ker f \oplus \operatorname{Im} f = \mathbb{R}^3$.

3. $V = \{(x, y, z) \in \mathbb{R}^3 \mid f((x, y, z)) = (x, y, z)\}$.

$$= \ker g \quad \text{où } g : (x, y, z) \mapsto f((x, y, z)) - (x, y, z)$$

g est linéaire.

Donc V est un sev de \mathbb{R}^3 .

$(x, y, z) \in V$

ssi $A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$

ssi $\begin{cases} 2x - y - z = x \\ -x + 2y - z = y \\ -x - y + 2z = z \end{cases}$

ssi $z = -x - y$.

Rem.
 $F = \{\pi \in \mathcal{M}_n(\mathbb{R}), \operatorname{Tr} \pi = 0\}$
 $F = \ker \operatorname{Tr}$ donc
 F est un sev.

Donc $V = \text{Vect} \left(\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right)$.

Donc $\left(\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right)$ base de V .

4. On a $\text{ker } f \oplus \text{Im } f = \mathbb{R}^3$.

$\text{Im } f = \text{Vect} \left(\begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} \right)$.

$\begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} \in V$ car $\begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$

$\begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} \in V$ car $\begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} = 2 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$.

Donc $f((2, -1, -1)) = (2, -1, -1)$,

$f((-1, 2, -1)) = (-1, 2, -1)$.

Donc pour tout $(x, y, z) \in \text{Im } f$, $f(x, y, z) = (x, y, z)$.

Donc pour tout $(x, y, z) \in \mathbb{R}^3 = \text{ker } f \oplus \text{Im } f$,

$(x, y, z) = \underbrace{(x_1, y_1, z_1)}_{\in \text{ker } f} + \underbrace{(x_2, y_2, z_2)}_{\in \text{Im } f}$

on a $f((x, y, z)) = \underbrace{f((x_1, y_1, z_1))}_{=0} + \underbrace{f((x_2, y_2, z_2))}_{(x_2, y_2, z_2)}$

$= (x_2, y_2, z_2)$.

Donc f est la projection sur $\text{Im } f$ // à $\text{ker } f$.

5. $B_1 = ((1, 1, 1))$ base de $\text{ker } f$

$B_2 = ((2, -1, -1), (-1, 2, -1))$ base de $\text{Im } f$ ∈ Im f ∈ Im f

$B = (B_1, B_2)$ base de \mathbb{R}^3

$B = (u_1, u_2, u_3)$
↑ ↑ ↑
ker f Im f Im f

$\text{mat}_B f = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ ← u_1
← u_2
← u_3

$f(u_2) = u_2$

$f(u_3) = u_3$

$$A = \text{mat}_{\mathcal{B}_C}^{\mathcal{B}} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \text{mat}_{\mathcal{B}}^{\mathcal{B}} \begin{pmatrix} 3 & & \\ & 3 & \\ & & 1 \end{pmatrix}$$

Donc $A = P \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} P^{-1}$,

P inversible car
matrice de
passage

d'où $P^{-1} A P = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$.

avec $P = \begin{pmatrix} 1 & 2 & -1 \\ 1 & -1 & 2 \\ 1 & -1 & -1 \end{pmatrix}$.