

Démonstration:

- Retrouver l'équation du mouvement du pendule

$$E_c = \frac{I}{2} \dot{\theta}^2$$

$$E_p = -mgd \cos \theta + cte$$

$$\delta W = 0$$

$$\frac{\partial L}{\partial x_i} = \frac{\partial}{\partial \dot{\theta}} \left[\frac{I}{2} \dot{\theta}^2 + mgd \cos \theta - cte \right]$$

$$= I \dot{\theta}$$

$$\frac{\partial}{\partial t} \left[\frac{\partial L}{\partial \dot{\theta}} \right] = I \ddot{\theta}$$

$$\frac{\partial L}{\partial x} = \frac{\partial}{\partial \theta} \left[\frac{I}{2} \dot{\theta}^2 + mgd \cos \theta - cte \right]$$

$$= -mgd \sin \theta$$

$$\text{Car } \frac{d}{dt} \left[\frac{\partial L}{\partial \dot{x}_i} \right] - \frac{\partial L}{\partial x_i} = Q_i, \text{ et } \delta W = 0$$

$$\Rightarrow I \ddot{\theta} + mgd \sin \theta = 0$$

par l'hypothèse des petits mouvements,

$$I \ddot{\theta} + mgd \theta = 0$$



Exercice 1

```
syms q wo
b='D2q+(wo^2)*q=0';
q=dsolve(b,'q(0)=1','Dq(0)=0');
q=subs(q,wo,2*pi);
%q = exp(-pi*t*2i)/2 + exp(pi*t*2i)/2

syms E
E=0.5*((diff(q))^2+(wo^2)*(q^2))
E=subs(E,wo,2*pi);
E=simplify(E)
%E*=2*pi^2,E* est constant
```